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FUNDAMENTAL AND SINGULAR SOLUTIONS OF LAMÉ EQUATIONS FOR MEDIA WITH ARBITRARY ELASTIC ANISOTROPY

by

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Abstract. Fundamental and singular solutions of Lamé equations for media with arbitrary elastic anisotropy are constructed on the basis of multipolar expansions (expansions in spherical harmonics) of symbols and the corresponding operators. Theorems of convergence are formulated. A posteriori error estimates are presented.

Keywords: fundamental solution, singular solution, Lamé equations, multipolar series, spherical harmonics

1. Introduction. Solution of the boundary-value problems by boundary integral equation methods needs fundamental solutions. For isotropic elastic medium solution of equations of equilibrium in the 3-dimensional case was constructed by Thomson (Lord Kelvin) (1848). Presumably, the first attempt for justification of Kelvin's heuristic procedure for the fundamental solution construction was undertaken by Somigliana (1885). Much later the main properties of the fundamental solution were studied by a specially developed limiting process by Sternberg et al. (1955, 1964) and Turteltaub and Sternberg (1968).

The first attempt to construct fundamental solution for anisotropic media goes back to Fredholm (1900) and Zeilon (1911), who used the Fourier transformation for symbol construction, but failed in inverting of Fourier transformation. By use of the Fourier transformation and Levi's method for reducing number of parameters, the fundamental solutions in a closed form were obtained by Kupradze and Basheleishvili (1954), Burchuladze (1960, 1963), Rizzo and Shippey (1970), Hatiashvili (1982) for

the two-parametric problems, when the three-dimensional displacement field depends upon two spatial variables (for media with monoclinic symmetry these are plane and anti plane problems). Construction of a parametrics for cylindrically anisotropic axially symmetric bodies was done by Kuznetsov (1990).

Analytical solutions for some specific kinds of elastic anisotropy in the 3-dimensional case were constructed by Kröner (1953), Bacheleishvili (1957), Kahniashvili (1957). In the case of weak anisotropy, asymptotic formulas for fundamental solution were obtained by Leibfrid (1957). Some properties of the fundamental solution for media with arbitrary elastic anisotropy, but without it explicit construction, were studied by Sáenz (1953). It should be noted that analytical expressions for the fundamental solution in \mathbb{R}^3 were obtained only for one narrow subclass of elastic orthotropy, which includes transverse isotropy.

Two principally different numerical methods are used for constructing fundamental solution in the 3-dimensional case and media with arbitrary elastic anisotropy: (i) method based on Radon's transformation; and, (ii) multipolar decomposition method.

Method based on Radon's transformation was proposed by Lifshits and Rozentsveig (1947). The analogous method later was used by Synge (1957) who exploited McConnell's approach (1951); Willis (1965); Vogel and Rizzo (1973); Wilson and Cruse (1978); Natroshvili (1984), whose work along with constructing fundamental solution, contains theoretical analysis of normal solvability and the Fredholm properties of the boundary integral operators. Radon's transformations were also used by Kapanadze (1987); Deb, Henry and Wilson (1991); Schclar (1994), whose work along with Radon's transformations contains description of a new method for solving boundary integral equations based on the theorem of duality for singular solutions. Sometimes the method based on Radon's transformations is referred to as the plane wave decomposition method, see John (1955). Numerical experiments carried out by Wilson and Cruse (1978) showed that this method is highly time consuming from computational point of view. To decrease computing time, these authors proposed to use spline approximations on the unit sphere.

Analysis of theoretical problems for potential type operators related to the second order elliptic differential equations and the corresponding boundary integral

operators is going back to Somigliana (1885), Fredholm (1900), and Tricomi (1927). For matrix differential operators of anisotropic elasticity the corresponding analysis was developed by Natrishvili (1984); see also Burchuladze and Gegelia (1985); Kuznetsov (1991); Natroshvili (1995), Jentsch and Natroshvili (1995); Jentsch, Natroshvili and Wendland (1998), (1999).

Construction of the fundamental solution can be done also by the multipolar expansions (expansions in spherical harmonics on the unit sphere). The idea of such expansions is due to Fredholm (1900) and Zeilon (1911). However, lack of the appropriate technique on inversion of the Fourier transforms of (homogeneous) symbols corresponding to operators with weak singularity did not allow to obtain final expressions for the fundamental solutions at that time. Similar difficulties were observed by Kroner (1953), Kinoshita and Mura (1956) and Bross (1960, 1965, 1968). Some ideas for use of harmonic polynomials for construction of the fundamental solution were given by Bezier (1967).

The complete theory of multipolar expansions for construction of singular operators was developed by Calderon and Zygmund (1957) and Mikhlin (1962). Analogous theory for operators with weak singularity was developed by Bochner (1955). Later method of multipolar decompositions was extrapolated by Kuznetsov (1989, 1995a) for construction of the fundamental solutions for equations of equilibrium, equations of free vibrations (Kuznetsov, 1996) and construction of some singular solutions of mechanics which correspond to kernels of the double-layer potentials and their derivatives (Kuznetsov, 1995a, b). Numerical algorithms based on the multipolar expansions are discussed by Perelmuter and Kuznetsov (1995). Theoretical considerations show (see Kuznetsov, 1989, 1995a) that the multipolar expansion method has advantage in computation time in comparison with methods based on Radon's transformation.

The following analysis is concerned with theoretical and numerical aspects of the multipolar expansion method for constructing fundamental and singular solutions of equations of equilibrium for 3D media with arbitrary elastic anisotropy.

2. Basic notations. For an anisotropic elastic medium equilibrium equations in terms of the displacement field can be written in the form:

$$\mathbf{A}(\partial_x)\mathbf{u}(\mathbf{x}) \equiv -\operatorname{div}_x \mathbf{C} \cdot \nabla_x \mathbf{u}(\mathbf{x}) = 0, \quad (1)$$

where \mathbf{A} is the 3×3 matrix differential operator of the equilibrium equations; \mathbf{u} is the displacement vector field, and \mathbf{C} is the fourth-order elasticity tensor, assumed to be positive definite:

$$\forall \mathbf{A} \quad \mathbf{A} \cdot \mathbf{C} \cdot \mathbf{A} > 0, \quad (2)$$

$\mathbf{A} \in \mathbb{R}^3 \otimes \mathbb{R}^3, \mathbf{A} \neq 0$

The medium itself is assumed to be homogeneous and hyperelastic. The latter ensures symmetry of the elasticity tensor regarded as operator acting in the six-dimensional space of symmetric second-order tensors:

$$\forall \mathbf{A}, \mathbf{B} \quad \mathbf{A} \cdot \mathbf{C} \cdot \mathbf{B} = \mathbf{B} \cdot \mathbf{C} \cdot \mathbf{A}. \quad (3)$$

$\mathbf{A}, \mathbf{B} \in \operatorname{sym}(\mathbb{R}^3 \otimes \mathbb{R}^3)$

Conditions (2) and (3) allow us to decompose the elasticity tensor (regarded as the linear operator in the 6-dimensional space of symmetric second-order tensors in \mathbb{R}^3) in the following tensorial product:

$$\mathbf{C} = \sum_{\alpha=1}^6 \lambda_{\alpha} \mathbf{S}_{\alpha} \otimes \mathbf{S}_{\alpha}, \quad \lambda_{\alpha} > 0, \quad (4)$$

where \mathbf{S}_{α} are symmetric second-order tensors forming an orthonormal set with respect to Euclidian norm:

$$\mathbf{S}_{\alpha} \cdot \mathbf{S}_{\beta} = \delta_{\alpha\beta}. \quad (5)$$

In (5) $\delta_{\alpha\beta}$ is the Kronecker symbol.

Application of the integral Fourier transform

$$g^\wedge(\xi) = \int_{\mathbb{R}^3} g(\mathbf{x}) \exp(-2\pi i \mathbf{x} \cdot \xi) dx, \quad \xi \in \mathbb{R}^3$$

to the differential operator in Eq. (1) gives matrix symbol of the operator \mathbf{A} :

$$\mathbf{A}^\wedge(\xi) = (2\pi)^2 \xi \cdot \mathbf{C} \cdot \xi. \tag{6}$$

It follows from (2) and (3) that symbol \mathbf{A}^\wedge is strongly elliptic:

$$\forall \mathbf{a}, \xi \quad \mathbf{a} \cdot \mathbf{A}^\wedge(\xi) \cdot \mathbf{a} > 0, \quad \mathbf{a}, \xi \in \mathbb{R}^3, \mathbf{a}, \xi \neq 0 \tag{7}$$

Expression (6) shows also that symbol \mathbf{A}^\wedge is (positive) homogeneous of degree 2 and analytic in \mathbb{R}^3 .

The definition of the fundamental solution implies the following identity:

$$\mathbf{A}^\wedge(\xi) \cdot \mathbf{E}^\wedge(\xi) = \mathbf{I}, \tag{8}$$

where \mathbf{E}^\wedge is the symbol of the fundamental solution, and \mathbf{I} is the unit (diagonal) matrix. The identity (8) allows us to represent the symbol \mathbf{E}^\wedge in the form

$$\mathbf{E}^\wedge(\xi) = \mathbf{A}^\wedge_0(\xi) / \det \mathbf{A}^\wedge(\xi), \tag{9}$$

where $\mathbf{A}^\wedge_0(\xi)$ is the cofactor of the symbol $\mathbf{A}^\wedge(\xi)$. Expression (9) shows that symbol \mathbf{E}^\wedge is also strongly elliptic, positively homogeneous of degree -2 , and $\mathbf{E}^\wedge(\xi) = C^\infty(\mathbb{R}^3 \setminus 0; \mathbb{R}^3 \otimes \mathbb{R}^3)$.

Fourier transform inversion applied to expression (9) gives

PROPOSITION 2.1. Fundamental solution \mathbf{E} of the equilibrium equations (1) is positively homogeneous of degree -1 and $\mathbf{E}(\mathbf{x}) \in C^\infty(\mathbb{R}^3 \setminus \{0\}; \mathbb{R}^3 \otimes \mathbb{R}^3)$.

3. Multipolar expansions for fundamental solution. Let symbol \mathbf{E}^\wedge be expanded in a series of spherical harmonics on the unit sphere $S \subset \mathbb{R}^3$:

$$\mathbf{E}^\wedge(\xi) = |\xi|^{-2} \sum_{n=0,2,\dots}^{\infty} \sum_{k=-n}^n \mathbf{E}_{nk} Y_n^k(\xi'), \quad \xi' = \xi/|\xi|, \quad (10)$$

where Y_n^k are spherical harmonic of degree n and of the order k , connected to the associated Legendre functions P_n^k in the following way:

$$Y_n^k(\xi') = \left(\frac{(2n+1)}{4\pi} \frac{(n-|k|)!}{(n+|k|)!} \right)^{1/2} \times P_n^{|k|}(\cos \theta) \times e^{ik\varphi}. \quad (11)$$

In expression (11) spherical and Cartesian coordinates are connected by the following relation:

$$\xi' = (\sin \theta \sin \varphi; \sin \theta \cos \varphi; \cos \theta).$$

Formulas for computing the associated Legendre functions are presented in the Appendix. It should be noted that spherical harmonics (11) form the complete orthonormal set in $L^2(S)$. Matrix coefficients \mathbf{E}_{nk} in (10) are determined by integration over the unit sphere in \mathbb{R}^3 :

$$\mathbf{E}_{nk} = \int_S \mathbf{E}^\wedge(\xi') Y_n^k(\xi') d\xi',$$

where $d\xi' = \sin \theta d\theta d\varphi$ is the Lebesgue measure induced on S .

REMARK 3.1. Summation in (10) is done on harmonics of the even order only. That is because: (i) the symbol \mathbf{E}^\wedge is strongly elliptic; and, (ii) expressions (8) and (9) ensure positive homogeneity of the symbol. Indeed, spherical harmonics of the even order are even on S , while harmonics of the odd order are odd: $Y_n^k(-\xi') = -Y_n^k(\xi')$.

PROPOSITION 3.1 (Kuznetsov, 1989). Series in (10) converges to the symbol \mathbf{E}^\wedge : a) in a weak topology in $\mathfrak{S}'(\mathbb{R}^3; \mathbb{R}^3 \otimes \mathbb{R}^3)$, where \mathfrak{S}' is the space of tempered distributions in \mathbb{R}^3 ; b) in $L^2(S; \mathbb{R}^3 \otimes \mathbb{R}^3)$; c) in $C_c(\mathbb{R}^3 \setminus 0; \mathbb{R}^3 \otimes \mathbb{R}^3)$, where C_c stands for topology of the compact convergence in $\mathbb{R}^3 \setminus 0$.

Proof of Proposition 3.1 follows directly from the right-hand side of (9) ensuring symbol \mathbf{E}^\wedge to be positive homogeneous of degree -2 and (real) analytic everywhere in $\mathbb{R}^3 \setminus 0$.

Now, application of Bochner's inverting formula (see, Stein, Ch.III, §3, Theorem 5) to terms in (10) gives the fundamental solution obtained also in the form of multipolar series:

$$\mathbf{E}(\mathbf{x}) = |\mathbf{x}|^{-1} \sum_{n=0,2,\dots}^{\infty} \gamma_n \sum_{k=-n}^n \mathbf{E}_{nk} Y_n^k(\mathbf{x}'), \quad \mathbf{x}' = \mathbf{x}/|\mathbf{x}|, \quad (12)$$

where parameters γ_n known as Bochner's multipliers, can be easily computed by the following formula (Stein, Ch.III, §3):

$$\gamma_n = (-1)^{n/2} \pi^{1/2} \frac{\Gamma(\frac{n+1}{2})}{\Gamma(\frac{n+2}{2})}. \quad (13)$$

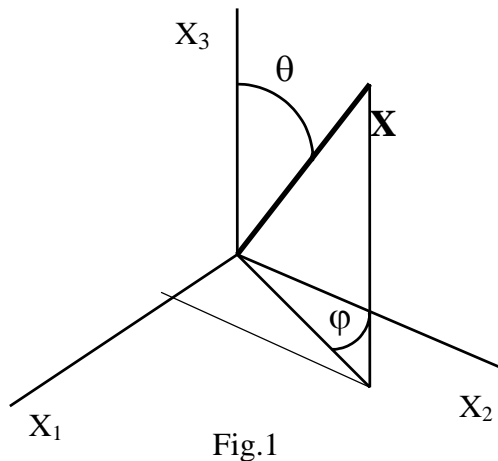
Expression (13) and Stirling's expansion for Γ -function allow us to obtain the following asymptotic formula:

$$|\gamma_n| = O(1), \quad n \rightarrow \infty. \quad (14)$$

Since the Fourier transformation sets topological isomorphism in the spaces $\mathfrak{S}'(\mathbb{R}^3; \mathbb{R}^3 \otimes \mathbb{R}^3)$, $L^2(S; \mathbb{R}^3 \otimes \mathbb{R}^3)$ and it is continuous in the space $C_c(\mathbb{R}^3 \setminus 0; \mathbb{R}^3 \otimes \mathbb{R}^3)$, Proposition 3.1 implies:

PROPOSITION 3.2. Series in the right side of (12) converges to the fundamental solution: a) in the weak topology in $\mathfrak{S}'(\mathbb{R}^3; \mathbb{R}^3 \otimes \mathbb{R}^3)$; b) in $L^2(S; \mathbb{R}^3 \otimes \mathbb{R}^3)$; c) in $C_c(\mathbb{R}^3 \setminus 0; \mathbb{R}^3 \otimes \mathbb{R}^3)$.

REMARK 3.2. a) The following notation for correspondence between Cartesian coordinates of the affine vector \mathbf{x} and its spherical coordinates θ, φ will be needed:



$$\theta = \arccos\left(\frac{x_3}{|\mathbf{x}|}\right), \quad \varphi = \arcsin\left(\frac{x_1}{|\mathbf{x}'|}\right),$$

where $\mathbf{x} \equiv (x_1; x_2; x_3)$ and $\mathbf{x}' = (x_1; x_2)$, refer to Fig. 1. These formulas for angles θ, φ are valid for any $\mathbf{x} \neq 0$;

b) It is known that summation of a harmonic series with coefficients having small errors may lead to an ill-posed problem in the specific pairs of metric spaces. To overcome possible difficulties a regularization method was proposed by Kuznetsov (1989). However, numerical experiments with some real anisotropic materials (see Perelmuter and Kuznetsov, 1995) revealed relatively fast convergence of multipolar series and numerical stability, so there was no need in applying regularization techniques.

4. Multipolar expansions for singular operators. When (i) the stress field produced by a single-layerd potential, or (ii) the displacement field produced by the double layer potential are needed, appropriate spatial derivatives can be obtained directly from the multipolar expansions of the principle symbol corresponding to the composition of the surface traction operator and the fundamental solution (when such a composition is restricted to the surface where the density is located, this produces a singular operator).

Application of the Fourier transformation to the composition

$$\mathbf{V}(\mathbf{y}) \equiv \mathbf{T}(\mathbf{v}_y, \partial_y) \cdot \mathbf{E}(\mathbf{y}), \tag{15}$$

where $\mathbf{T}(\mathbf{v}_y, \partial_y) \equiv \mathbf{v}_y \cdot \mathbf{C} \cdot \nabla_y$ is the surface traction operator, produces the following matrix principle symbol:

$$\mathbf{V}^\wedge(\mathbf{y}, \boldsymbol{\xi}) = 2\pi i (\mathbf{v}_y \cdot \mathbf{C} \cdot \boldsymbol{\xi}) \cdot \mathbf{E}^\wedge(\boldsymbol{\xi}). \quad (16)$$

In (15), (16) \mathbf{v}_y denotes field of the unit normals to the supporting surface (surface where the potential densities are located). In obtaining (16) the usual technique of “freezing” coefficients is used.

REMARK 4.1. a) Kernel (15) produces an important type of operators, called the double layer potentials (see, Kupradze et al., Ch.II, §4):

$$\mathbf{V}[\mathbf{f}](\mathbf{x}) \equiv \int_{\partial\Omega} \mathbf{f}(\mathbf{y}') \cdot (\mathbf{T}(\mathbf{v}_{y'}, \partial_{y'}) \cdot \mathbf{E}(\mathbf{x} - \mathbf{y}')) dy', \quad (17)$$

where $\partial\Omega$ is a 2-dimensional piecewise smooth manifold in \mathbb{R}^3 ; \mathbf{f} is an integrable on $\partial\Omega$ function, and dy' is the Lebesgue measure concentrated on $\partial\Omega$. It should be noted that field $\mathbf{v}_{y'}$ is defined only for regular points of $\partial\Omega$. When $\mathbf{x} \in \partial\Omega$, the integral in (17) is evaluated as the Principle Value (P.V.) integral.

b) In the subsequent analysis kernels and the corresponding operators will be denoted by the same letter.

Some obvious properties of the principle symbol \mathbf{V}^\wedge are stated in the following proposition

PROPOSITION 4.1. At any fixed regular point $\mathbf{y} \in \partial\Omega$, the principle symbol $\mathbf{V}^\wedge(\mathbf{y}, \boldsymbol{\xi})$ is a) real-analytic in $\mathbb{R}^3 \setminus 0$ with respect to $\boldsymbol{\xi}$ -variable; b) homogeneous of degree -1 with respect to $\boldsymbol{\xi}$ -variable, but not positive homogeneous.

Multipolar expansion of this symbol yields

$$\mathbf{V}^\wedge(\mathbf{y}, \boldsymbol{\xi}) = |\boldsymbol{\xi}|^{-1} \sum_{n=1,3,\dots}^{\infty} \sum_{k=-n}^n \mathbf{V}_{nk}(\mathbf{y}) Y_n^k(\boldsymbol{\xi}'), \quad \boldsymbol{\xi}' = \boldsymbol{\xi}/|\boldsymbol{\xi}|, \quad (18)$$

where matrix coefficients \mathbf{V}_{nk} are determined by integration of the symbol \mathbf{V}^\wedge on the unit sphere:

$$\mathbf{V}_{nk}(\mathbf{y}) = \int_S \mathbf{V}^\wedge(\mathbf{y}, \boldsymbol{\xi}') Y_n^k(\boldsymbol{\xi}') d\boldsymbol{\xi}'.$$

Series in the right-hand side of (18) contains harmonics of the odd order only; this follows from Proposition 4.1.b and Remark 3.1.

PROPOSITION 4.2. a) At any fixed regular point $\mathbf{y} \in \partial\Omega$ series in the right-hand side of (18) converges to the symbol \mathbf{V}^\wedge : a) in the weak topology in $\mathfrak{S}'(\mathbb{R}^3; \mathbb{R}^3 \otimes \mathbb{R}^3)$; b) in $L^2(S; \mathbb{R}^3 \otimes \mathbb{R}^3)$; c) in $C_c(\mathbb{R}^3 \setminus 0; \mathbb{R}^3 \otimes \mathbb{R}^3)$.

Proof of Proposition 4.2 is analogues to the proof of Proposition 3.1.

Application of Bochner's inverting formula to the terms in expansion (18) gives kernel \mathbf{V} :

$$\mathbf{V}(\mathbf{y}, \mathbf{x}) = |\mathbf{x}|^{-2} \sum_{n=1,3,\dots}^{\infty} \gamma'_n \sum_{k=-n}^n \mathbf{V}_{nk}(\mathbf{y}) Y_n^k(\mathbf{x}'), \quad \mathbf{x}' = \mathbf{x}/|\mathbf{x}|, \quad (19)$$

where coefficients \mathbf{V}_{nk} depend upon “frozen” variable \mathbf{y} , and multipliers γ'_n admit the following representation (Stein, Ch.III, §3):

$$\gamma'_n = i^n \pi^{-1/2} \frac{\Gamma(\frac{n+2}{2})}{\Gamma(\frac{n+1}{2})} \quad (20)$$

Comparing (18), (19) shows that the left-hand side of (19) is real valued and real analytic in $\mathbb{R}^3 \setminus 0$.

Similarly to the fundamental solution, multipolar series (19) has the following properties:

PROPOSITION 4.3. At any fixed regular point $\mathbf{y} \in \partial\Omega$ series in the right-hand side of (19) converges to the distribution defined by its kernel \mathbf{V} : a) in the weak topology in $\mathfrak{S}'(\mathbb{R}^3; \mathbb{R}^3 \otimes \mathbb{R}^3)$; b) in $L^2(S; \mathbb{R}^3 \otimes \mathbb{R}^3)$; c) in $C_c(\mathbb{R}^3 \setminus 0; \mathbb{R}^3 \otimes \mathbb{R}^3)$.

REMARK 4.2. a) The distribution identified with its kernel \mathbf{V} and acting on functions with the non-thin support in \mathbb{R}^3 represents operator with weak (integrable) singularity, while restriction of this operator on functions having support on a two-dimensional manifold, forces to regard it as a singular operator;

b) From computational point of view it is more convenient to expand in multipolar series the tensorial symbol

$$\mathbf{V}' \wedge (\boldsymbol{\xi}) = 2\pi i (\mathbf{C} \cdot \boldsymbol{\xi}) \cdot \mathbf{E} \wedge (\boldsymbol{\xi}), \quad (21)$$

which is the three-valent symbol. Expanding such a symbol into multipolar series, then applying Bochner's inverting formula, and making convolution with the field of the unit normals \mathbf{v} , produces the desired kernel \mathbf{V} .

5. Multipolar expansions for hyper-singular operators. In this section construction of the composition of the surface traction operator and the operator of the double-layer potential is regarded:

$$\mathbf{W}(\mathbf{z}, \mathbf{y}, \mathbf{x}) \equiv \mathbf{T}(\mathbf{v}_z, \partial_x) \cdot \mathbf{V}^t(\mathbf{y}, \mathbf{x}), \quad (22)$$

where \mathbf{W} is kernel of the corresponding pseudodifferential (hyper-singular) operator; upper index t stands for transposition of the matrix-valued operator \mathbf{V} .

“Freezing” variables and applying Fourier transformation to (22), produces the following amplitude (see, Treves, Ch.1, §2 for the definition of amplitudes):

$$\mathbf{W}^\wedge(\mathbf{z}, \mathbf{y}; \boldsymbol{\xi}) = -(2\pi)^2 (\mathbf{v}_z \cdot \mathbf{C} \cdot \boldsymbol{\xi}) \cdot \mathbf{E}^\wedge(\boldsymbol{\xi}) \cdot (\boldsymbol{\xi} \cdot \mathbf{C} \cdot \mathbf{v}_y). \quad (23)$$

In obtaining (23) we assigned different variables appearing in the “frozen” coefficients in (16) and (22).

Routine procedure similar to one exploited for obtaining (17), (19) produces the kernel \mathbf{W} in the form of multipolar series:

$$\mathbf{W}(\mathbf{z}, \mathbf{y}, \mathbf{x}) = |\mathbf{x}|^{-3} \sum_{n=0,2,\dots}^{\infty} \gamma_n'' \sum_{k=-n}^n \mathbf{W}_{nk}(\mathbf{z}, \mathbf{y}) Y_n^k(\mathbf{x}'), \quad \mathbf{x}' = \mathbf{x}/|\mathbf{x}|, \quad (24)$$

where in contrast to (17), (19) series in the right-side of (24) contains harmonics of the even order only, that is because of positive homogeneity of the amplitude with respect to $\boldsymbol{\xi}$ -variable. Matrix coefficients \mathbf{W}_{nk} are determined by integration of the amplitude (23) on the unit sphere in \mathbb{R}^3 similarly to obtaining \mathbf{V}_{nk} .

Bochner's multipliers γ_n'' in (24) have the following form:

$$\gamma_n'' = (-1)^{n/2} \pi^{-3/2} \frac{\Gamma(\frac{n+3}{2})}{\Gamma(\frac{n}{2})} \quad (25)$$

The following Proposition is analogues to Proposition 4.3:

PROPOSITION 5.1. At any fixed regular points $\mathbf{y}, \mathbf{z} \in \partial\Omega$ series in the right-hand side of (24) converges to the distribution associated with its kernel \mathbf{W} : a) in the weak topology in $\mathfrak{S}'(\mathbb{R}^3; \mathbb{R}^3 \otimes \mathbb{R}^3)$; b) in $L^2(S; \mathbb{R}^3 \otimes \mathbb{R}^3)$; c) in $C_c(\mathbb{R}^3 \setminus \{0\}; \mathbb{R}^3 \otimes \mathbb{R}^3)$.

REMARK 5.1. a) At fixed regular points $\mathbf{z}, \mathbf{y} \in \partial\Omega$, operator \mathbf{W} acting on functions with the non-thin support in \mathbb{R}^3 , becomes an operator with strong (non-integrable) singularity. Kernel of the operator \mathbf{W} can be represented in the form

$$\mathbf{W}(\mathbf{z}, \mathbf{y}, \mathbf{x}) = \mathbf{W}_0(\mathbf{z}, \mathbf{y})\delta(\mathbf{x}) + \mathbf{W}_1(\mathbf{z}, \mathbf{y}, \mathbf{x}), \quad \mathbf{z}, \mathbf{y} \in \partial\Omega, \quad \mathbf{x} \in \mathbb{R}^3, \quad (26)$$

where \mathbf{W}_0 is a matrix piecewise-smooth function defined on the manifold $\partial\Omega$; $\delta(\mathbf{x})$ is the delta-function in \mathbb{R}^3 ; and \mathbf{W}_1 is the kernel of a singular operator (with respect to \mathbf{x} -variable) having zero mean value:

$$\forall \mathbf{z}, \mathbf{y} \in \partial\Omega \quad \int_S \mathbf{W}_1(\mathbf{z}, \mathbf{y}, \mathbf{x}') dx' = 0. \quad (27)$$

Condition (27) is due to decomposition (26) where the first term in the right-hand side is responsible for non-zero mean value.

b) Restriction of the operator \mathbf{W} on functions having support on the manifold $\partial\Omega$, forces to regard it as the hyper-singular operator. By analogy with Remark 4.1.a, we can define

$$\mathbf{W}[\mathbf{f}](\mathbf{x}) = \text{F.P.} \int_{\partial\Omega} \mathbf{T}(\mathbf{v}_x, \partial_x) \cdot \left(\mathbf{f}(\mathbf{y}') \cdot \left(\mathbf{T}(\mathbf{v}_{y'}, \partial_{y'}) \mathbf{E}(\mathbf{x} - \mathbf{y}') \right) \right) dy', \quad \mathbf{x} \in \partial\Omega,$$

where the corresponding hyper-singular integral is evaluated as the finite part (F.P.) integral (see, Edwards, Ch.5, §5). An example of the explicit regularization technique for evaluating the F.P. integral is given in (Kuznetsov, 1995b).

c) From computational point of view it is more convenient to expand the following tensorial symbol in the multipolar series:

$$\mathbf{W}'^{\wedge}(\xi) = -(2\pi)^2 \mathbf{C} \cdot (\xi \otimes \mathbf{E}^{\wedge}(\xi) \otimes \xi) \cdot \mathbf{C}, \quad (28)$$

where \mathbf{W}'^{\wedge} is the four-valent symbol. Applying to thus obtained multipolar series Bochner's inverting formula and then taking convolution from both sides with the vector fields $\mathbf{v}_z, \mathbf{v}_y$, produces the desired kernel \mathbf{W} .

6. Error estimates. Suppose that: (i) multipolar series (10) and (12) are truncated and contain harmonics of degree up to N ; and, (ii) matrix coefficients \mathbf{E}_{nk} contain computational errors, except coefficient \mathbf{E}_{00} (solid harmonic), which is assumed to be defined precisely. Substituting such a truncated expansion for the fundamental solution in the equations of equilibrium (1) yields

$$\mathbf{A}(\partial_x) \mathbf{E}_N(\mathbf{x}) = \delta(\mathbf{x}) \mathbf{I} + \mathbf{K}_N(\mathbf{x}) \quad (29)$$

where $\mathbf{E}_N(\mathbf{x})$ is the approximate fundamental solution due to truncation and computational errors, and $\mathbf{K}_N(\mathbf{x})$ is a matrix residual operator.

REMARK 6.1. Approximate fundamental solution $\mathbf{E}_N(\mathbf{x})$ is of class -2 in \mathbb{R}^3 , this follows from the multipolar expansions (10), (12). Now, left-hand side of (29) ensures that operator \mathbf{K}_N is of class 0 in \mathbb{R}^3 .

PROPOSITION 6.1. Operator \mathbf{K}_N in the right-hand side of (29) is singular integral operator in \mathbb{R}^3 .

Proof. Fourier transformation applied to both sides of (29) gives

$$\mathbf{K}_N^\wedge(\boldsymbol{\xi}) = \mathbf{A}^\wedge(\boldsymbol{\xi}) \cdot (\mathbf{E}^\wedge(\boldsymbol{\xi}) - \mathbf{E}_N^\wedge(\boldsymbol{\xi})) \quad (30)$$

In obtaining (30), relation (8) was used. Since the right-hand side of (30) is positive homogeneous of degree 0, and the operator \mathbf{K}_N satisfies condition of zero mean value on the unit sphere (that is due to (29) and the condition (ii) preceding (29)), \mathbf{K}_N appears to be the singular operator in \mathbb{R}^3 .

The Plancherel theorem applied to the operator \mathbf{K}_N , shows that its (operator) L^2 -norm can be majored by the corresponding L^∞ -norm of the symbol \mathbf{K}_N^\wedge (see, Stein, Ch. II, §1, n. 1.4). Both norms are equivalent for scalar operators. Due to homogeneity of degree 0 of the symbol \mathbf{K}_N^\wedge , it is natural to evaluate L^∞ -norm of this symbol on the unit sphere $S \subset \mathbb{R}^3$.

Let K_N^{pq} denotes the p, q -component of the symbol \mathbf{K}_N^\wedge :

$$K_N^{pq}(\xi') = \delta^{pq} - (2\pi)^2 \sum_{n=0,2,\dots}^N \sum_{k=-n}^n C^{prst} \frac{\xi_r \xi_s}{|\xi|^2} \tilde{E}_{nk}^{tq} Y_n^k(\xi'), \quad (31)$$

$$p, q = 1, 2, 3$$

where \tilde{E}_{nk}^{tq} are corresponding coefficients of the fundamental solution \mathbf{E}_N . Introducing scalar

$$\Delta_N = \sup_{1 \leq p \leq 3} \sup_{\xi' \in S} \left(\sum_{q=1}^3 |K_N^{pq}(\xi')| \right), \quad (32)$$

which majorizes the spectral L^∞ -norm of the symbol $\hat{\mathbf{K}}_N$ (see, Marcus and Mink, Ch. III, § 1.6.5), we obtain natural estimate for precision of the numerically constructed fundamental solution \mathbf{E}_N . In fact, due to (29), (32) and the Plancherel's theorem, we have $\Delta_N \geq \|\mathbf{K}_N\|_{(L^2, L^2)} = \|A(\partial_x)\mathbf{E}_N - \delta\mathbf{I}\|_{(L^2, L^2)}$, where (L^2, L^2) is the corresponding operator norm.

Numerical analysis developed by Kuznetsov (1989) showed that multipolar series rather rapidly converge for the tested kinds of elastic anisotropy. For example, a good accuracy with the error estimate $\Delta_N \approx 10^{-5}$ has been achieved for the following orthotropic material:

$$\begin{aligned} C^{1111} &= 1.091; & C^{1122} &= 2.429; & C^{1133} &= 5.036; \\ & & C^{2222} &= 1.209; & C^{2233} &= 1.210; \\ & & & & C^{3333} &= 1.091; \\ C^{1212} &= 0.082; & C^{2323} &= 0.068; & C^{3131} &= 0.074 \end{aligned}$$

by the truncated series ($N = 6$) corresponding to 49 spherical harmonics. Computations were carried out with the real numbers having mantissa with ~15 decimal digits. Higher accuracy with $\Delta_N \approx 10^{-8}$ was achieved at $N = 12$, while further

increasing parameter N up to 20 harmonics did not reveal any improvements of the accuracy, that was because of the irreducible computational errors.

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APPENDIX

Formulas for Legendre polynomials and functions

The following formula, which is due to Hobson (1931), gives Legendre polynomials in the convenient for computational purposes form:

$$P_n(x) = 2^{-n} \sum_{k=0}^{E(n/2)} \frac{(-1)^k (2n-2k)!}{k!(n-k)!(n-2k)!} x^{n-2k} \quad (\text{A1})$$

where $E(n/2)$ denotes the entire part of $n/2$.

On obtaining coefficients of the polynomial $P_n(x)$, the associated Legendre functions P_n^k can be computed by the following analytical formulas

$$P_n^k(x) = (-1)^k (1-x^2)^{k/2} \frac{d^k}{dx^k} P_n(x) \quad (\text{A2})$$

Combination of (A1) and (A2) produces

$$P_n^k(x) = 2^{-n} (-1)^k (1-x^2)^{k/2} \times \quad (\text{A3})$$

$$\sum_{m=0}^{E(n/2)-k} \frac{(-1)^m (2n-2m)!(n-2m)!}{m!(n-m)!(n-2m)!(n-2m-k)!} x^{n-2m-k}$$

The associated Legendre functions P_n^k can also be obtained by combination of two recurrence relations, which are mainly due to Magnus and Oberhettinger (1948):

$$P_{n+1}^k(x) = (n-k+1)^{-1} \left[(2n+1)xP_n^k(x) - (n+k)P_{n-1}^k(x) \right] \tag{A4}$$

$$1 \leq n, \quad 0 \leq k \leq n-1$$

and

$$(1-x^2)^{1/2} P_n^{k+2}(x) = 2(k+1)x P_n^{k+1}(x) - (n(n+1) - k(k+1)) (1-x^2)^{1/2} P_n^k(x)$$

$$0 \leq k \leq n-2 \tag{A5}$$

where (A4) can be applied for computing P_n^1 , while (A5) for P_n^k , $k > 1$.

It can easily be deduced from (A2) that $P_n^n = 1$; P_n^0 coincides with the corresponding Legendre polynomial, and $P_n^k \equiv 0$ at $k > n$.

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